

Jason T. Isaacs

Computer Science and Information Technology
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— Education

Ph.D. University of California, Santa Barbara, Electrical and Computer Engineering, March 2012
Dissertation: *UAV Data Mule Vehicle Routing Problems In Sparse Sensor Networks*
Adviser: João P. Hespanha

M.S. University of California, Santa Barbara, Electrical and Computer Engineering, June 2008
Major: Control Systems
Minor: Signal Processing

B.S. University of Kentucky, Electrical Engineering, *Summa Cum Laude*, Dec. 1999

B.S. Eastern Kentucky University, Engineering Physics, *Magna Cum Laude*, Dec. 1999

— Teaching Experience

Assistant Professor, August 2015–Present
California State University, Channel Islands, Dept. of Computer Science and Information Technology

— Courses Taught

S2017

COMP 462 Embedded Systems
COMP 490 Topics in Computer Science: NASA Swarmathon
COMP 499 Capstone Project
COMP 597 Master Thesis
IT 491 Capstone Preparation
IT 499 Capstone Project

F2016

COMP 150 Introduction to Object Oriented Programming
COMP 491 Capstone Preparation
COMP 597 Master Thesis
IT 491 Capstone Preparation

S2016

COMP 150 Introduction to Object Oriented Programming
COMP 462 Embedded Systems
COMP 494 Independent Research
COMP 590 Advanced Topics In Computer Science

F2015

COMP 150 Introduction to Object Oriented Programming
COMP 491 Capstone Preparation

— Other Work Experience

Visiting Assistant Researcher, July 2016 – Present
University of California, Santa Barbara, Center for Control, Dynamical-Systems, and Computation

Co-founder, January 2014 – July 2016
ShadowMaps Inc.

Post-doctoral Scholar, March 2012–April 2015
University of California, Santa Barbara, Center for Control, Dynamical-Systems, and Computation

Research Intern, Summer 2008
United States Army Research Laboratory

Senior Hardware Development Engineer, January 2000 – August 2006
Lexmark International Inc.

— Honors and Awards

NASA Swarmathon Physical Competition, Stipend and Hardware Totaling \$6000, August 2016

California State University, Channel Islands, Minigrant Internal Grant, \$9000, March 2016

California State University, Channel Islands, RSCA Internal Grant, \$6500, March 2016

California State University, Channel Islands, Lottery Fund Internal Grant, \$3500, November 2015

Best Demo (runner-up), ACM MobiCom, September 2014

Best Paper Award, ACM MobiCom S3 Workshop Wireless of the Students, by the Students, for the Students, September 2014

Best Demo, Goleta Entrepreneurial Magnet (GEM) Summer Accelerator, September 2014

Grand Prize, UCSB Technology Management Program, New Venture Competition, May 2014

Best Presentation in Session, American Control Conference, July 2011

School For Scientific Thought Teaching Fellowship, California Nanoscale Institute, May 2010

Doctoral Scholar Fellowship, UCSB Graduate Division, September 2006-September 2010

— Selected Talks

Introduction to the AVES Lab, Channel Islands Chapter of Association of Unmanned Vehicle Systems International (AUVSI), Camarillo, California, September 13, 2016

Dynamic Vehicle Routing over a Sparse Sensor Network, INFORMS 2011, Charlotte, North Carolina, November 15, 2011

Information-Based Optimal Navigation, 18th IFAC World Congress Workshop on Multiple Vehicle Motion Planning, Navigation, and Control - Theory and Practice, Milan, Italy, August 28, 2011

Dynamic Vehicle Routing over a Sparse Sensor Network, 20th Southern California Nonlinear Control Workshop, U. C. Riverside, May 13, 2011

Optimal TDOA Sensor Placement For Uncertain Source Locations, 17th Southern California Nonlinear Control Workshop, Caltech, May 22, 2009

— Professional Service

Technical Reviewer

IEEE Conference on Decision and Control \diamond IFAC World Congress \diamond IFAC Workshop on Distributed Estimation and Control in Networked Systems \diamond International Conference on Control, Automation, Robotics and Vision \diamond IEEE Transactions on Wireless Communications \diamond American Control Conference \diamond IEEE Transactions on Signal Processing \diamond IEEE Transactions on Control Systems Technology \diamond IEEE Sensors Journal \diamond International Conference on Intelligent Robots and Systems \diamond Robotics and Autonomous Systems \diamond Journal of Optimization Theory and Applications \diamond Unmanned Systems Journal \diamond NSF Panelist

Session Chair

55th IEEE Conference on Decision and Control, "Kalman Filtering"

18th IFAC World Congress, "New Approaches in Control Education"

— Professional Affiliations

Institute for Electrical and Electronics Engineers (IEEE) \diamond IEEE Control Systems Society (IEEE CSS) \diamond IEEE Robotics and Automation Society (IEEE RAS) \diamond Association of Unmanned Vehicle Systems International (AUVSI)

— Outreach

Summer Robotics Challenge Mentor, University of California, Santa Barbara, 2010-2013

Santa Barbara High School Robotics Course Instructor, Santa Barbara High School, 2012

School for Scientific Thought Robotics Course Instructor, University of California, Santa Barbara, 2010

Family Ultimate Science Exploration (FUSE) Mentor, 2009-2010

Publications

Journal Articles

- [1] D. J. Klein, S. Venkateswaran, J. T. Isaacs, J. Burman, J. P. Hespanha, and U. Madhow. Source Localization in a Sparse Acoustic Sensor Network using UAVs as Information Seeking Data Mules. *ACM Transactions on Sensor Networks*, 9(3), August 2013.
- [2] J. T. Isaacs, J. P. Hespanha. Dubins Traveling Salesman with Neighborhoods: A Graph-Based Approach. *Algorithms*, 6(1): 84–99, February 2013.
- [3] C. E. Laird, B. A. Harmon, C. A. Wilson, D. L. Hunter, and J. T. Isaacs. Low energy response calibration of the BATSE large area detectors onboard the Compton Observatory. *Nuclear Instruments and Methods in Physics Research Section A: Accelerators, Spectrometers, Detectors and Associated Equipment*, 566(2): 433–441, October 2006.

Proceedings

- [4] J. T. Isaacs, K. O. Ezal, J. P. Hespanha. Local Carrier-Based Precision Approach and Landing System. In *Proceedings of the 55th IEEE Conference on Decision and Control*, December 2016.
- [5] A. T. Irish, J. T. Isaacs, D. Iland, J. P. Hespanha, E. M. Belding, and U. Madhow. Demo: ShadowMaps, the Urban Phone Tracking System. In *Proceedings of the ACM International Conference on Mobile Computing and Networking*, September 2014.
- [6] A. T. Irish, D. Iland, J. T. Isaacs, J. P. Hespanha, E. M. Belding, and U. Madhow. Using Crowdsourced Satellite SNR Measurements for 3D Mapping and Real-Time GNSS Positioning Improvement. In *Proceedings of the ACM Workshop on Wireless of the Students, by the Students, for the Students*, September 2014.
- [7] J. T. Isaacs, F. Quitin, L. R. Garcia Carrillo, U. Madhow, and J. P. Hespanha. Quadrotor Control for RF Source Localization and Tracking. In *Proceedings of the 2014 International Conference on Unmanned Aircraft Systems*, May 2014.
- [8] J. T. Isaacs, C. Magee, A. Subbaraman, F. Quitin, K. Fregene, U. Madhow, and J. P. Hespanha. GPS-Optimal Micro Air Vehicle Navigation in Degraded Environments. In *Proceedings of the 2014 American Control Conference*, June 2014.
- [9] A. T. Irish, J. T. Isaacs, F. Quitin, J. P. Hespanha, and U. Madhow. Belief Propagation Based Localization and Mapping Using Sparsely Sampled GNSS SNR Measurements. In *Proceedings of the 2014 IEEE International Conference on Robotics and Automation*, June 2014.
- [10] J. T. Isaacs, A. T. Irish, F. Quitin, U. Madhow, and J. P. Hespanha. Bayesian Localization and Mapping Using GNSS SNR Measurements. In *Proceedings of the IEEE/ION Position Location and Navigation Symposium*, May 2014.
- [11] A. T. Irish, J. T. Isaacs, F. Quitin, J. P. Hespanha, and U. Madhow. Probabilistic 3D Mapping based on GNSS SNR Measurements. In *Proceedings of the 2014 IEEE International Conference on Acoustics, Speech, and Signal Processing*, April 2014.
- [12] S. Venkateswaran, J. T. Isaacs, K. Fregene, R. Ratmansky, B. M. Sadler, J. P. Hespanha, and U. Madhow. RF Source-Seeking by a Micro Aerial Vehicle using Rotation-Based Angle of Arrival Estimates. In *Proceedings of the 2013 American Control Conference*, June 2013.
- [13] J. T. Isaacs, S. Venkateswaran, J. P. Hespanha, U. Madhow, J. Burman, and T. Pham. Multiple Event Localization in a Sparse Acoustic Sensor Network Using UAVs as Data Mules. In *Proceedings of the 3rd International Workshop on Wireless Networking & Control for Unmanned Autonomous Vehicles: Architectures, Protocols and Applications*, December 2012.

- [14] J. T. Isaacs, D. J. Klein, and J. P. Hespanha. A Guided Internship For High School Students Using iRobot Create. In *Proceedings of the 18th IFAC World Congress*, September 2011.
- [15] J. T. Isaacs, D. J. Klein, and J. P. Hespanha. Algorithms for the Traveling Salesman Problem with Neighborhoods Involving a Dubins Vehicle. In *Proceedings of the 2011 American Control Conference*, July 2011.
- [16] D. J. Klein, J. J. Schweikl, J. T. Isaacs, and J. P. Hespanha. On UAV Routing Protocols for Sparse Sensor Data Exfiltration. In *Proceedings of the 2010 American Control Conference*, June 2010.
- [17] J. T. Isaacs, D. J. Klein, and J. P. Hespanha. Optimal Sensor Placement For Time Difference of Arrival Localization. In *Proceedings of the 48th IEEE Conference on Decision and Control*, December 2009.